# An Historical Analysis of the California Current using ROMS 4D-Var: 1980-2010

Emilie Neveu, Andrew Moore, Chris Edwards, Jérôme Fiechter, Patrick Drake, Emma Nuss\*, Selime Gürol\*\*, Anthony Weaver\*\* Ocean Science Department, University of California of Santa Cruz, USA; \*University of California of San Diego, USA; \*\* CERFACS, Toulouse, France

## Model Set-up: ROMS CCS (California Current System)

Pronounced seasonal cycle of upwelling in Central California coast / Energetic mesoscale circulations

Bathymetry/Domain : Along the California Coast



- Error covariance matrix D uses diffusion operator approach  $\mathbf{D} = \operatorname{diag}(\mathbf{B}_{\mathbf{x}}, \mathbf{B}_{\mathbf{f}}, \mathbf{B}_{\mathbf{b}})$
- Based on [Weaver et al. (2005)]
- prior initial state composed on unbalanced components assumed to be uncorrelated: Diagonal matrix of standard deviations
  - $\mathbf{B}_{\mathbf{x}} = \mathbf{\Sigma} \mathbf{C} \mathbf{\Sigma}^{T}$
  - Univariate correlation matrix, modeled as pseudo-diffusion
- standard deviations computed from a long run without assimilation
- Decorrelation lengths:
- $-B_x$ : 50km horizontal, 30m vertical
- $-B_{f}$ : 300km (wind stress), 100km (heat/freshwater)

#### Departures from Observation

Assimilated Sea Surface Temperature Observations









#### Regional Ocean Modeling System



- 1/10° horizontal resolution
- 42 s-levels following bathymetry : 0.3-8m over continental shelf ; 7-300m deep ocean
- Surface forcing and open boundaries compute daily and interpolated
- Forcing  $f^{b}(t)$ 
  - atmospheric boundary layer fields, freshwater fluxes: ERA 40 / 2.5° (1980- 2001), ERA interim Projects / 0.7° (2002-2010)
  - winds, 6h averaged from: ERA 40 / 2.5° (1980- 2001), Cross Calibrated MultiPlatform (CCMP)/ 25km (1987-2010), ERA interim Projects / 0.7° (2002-2010)
- ocean surfaces fluxes : derived using bulk formulation of [Liu et al. (79)], [Fairfall et al. (96)]

- $-B_{b}$ : 100km horizontal, 30m vertical
- Correlation lengths: semi-variogram method, [Bannerjee et.al, (04)] [Millif et al.(03)]
- Incremental method, tangent linear hypothesis Tangent linear observation operator + Tangent linear model
- Control vector  $\mathbf{z} = \mathbf{z}^b + \delta \mathbf{z}$  $J = \delta \mathbf{z}^T \mathbf{D}^{-1} \delta \mathbf{z} + (\mathbf{d} - \mathbf{G} \delta \mathbf{z})^T \mathbf{R}^{-1} (\mathbf{d} - \mathbf{G} \delta \mathbf{z})$
- Assumed small non-linearities
- Innovation vector  $\mathbf{y}^o H(\mathbf{x})$
- Cycles of 15 inner-loops: minimization of J, 1 outer-loop to update the innovation
- For each cycle: B-preconditioned restricted Lanczos method
- Minimization of J using an adjoint model, searching for  $\delta z$  in the observation space
- Optimization method : Lanczos version of the Restricted Preconditioned Conjugate Gradient (RPCG) of [Gratton, Tshimanga, 2009], same rate of convergence as primal method.

#### **Background quality control**

Reject observation subject to gross errors or inconsistent with the model using the following criteria



• Threshold values  $\alpha$  estimated from frequential distribution f of innovation vectors **d** 

California Cooperative Oceanic Fisheries Investigations- Calcofi Cruises (1990-2007)





### Variability

To understand seasonal to inter-annual and inter-decadal variability

#### Time-frequency analysis based on wavelet decomposition

- Compute wavelet coefficients Wav(time, period) for time series of variables (spatially averaged for each cycle)
- Plot  $|Wav|^2$ , the power wavelet; compare to the red-noise  $\mathbf{r}(t_i) = \alpha \mathbf{r}(t_{i-1}) + G(0, \sigma)$ , with  $\alpha$  chosen so that the Fourier transform of the red noise fits  $\frac{1}{T} \sum |Wav(time, period)|^2$ ; [Torrence, Compo (98)]
- Non-periodic signal padded with zeros to limit the boundaries reflection effect.
- Non-orthogonal Morlet wavelet : focus on the smooth/continuous variations of the timeseries

- Open boundary conditions  $\mathbf{b}^{b}(t)$ : North-South-West
- tracer/velocity fields: Simple Ocean Data Assimilation Product (SODA), Levitus seasonal climatology
- free surface: Chapman boundary condition, vertically integrated flow: Flather boundary condition
- Sponge layer for viscosity of 100 km, from 4 m<sup>2</sup>.s<sup>-1</sup> to 400 m<sup>2</sup>.s<sup>-1</sup>

### **Observations**

- All data from in-situ and satellites available were used
- all observation of the same state were combined as super-observation over 6h- time window to reduce redundancy
- diagonal error covariance matrix: sum of measurement and representativeness errors

#### Summary of the different Observations Platforms

Observation	Observing	Source	Combined	Period
Туре	Platform		Error	Covered
SSH	Altimeter	Aviso, 1 day average	0.04 m	1993-2010
SST	AVHRR/	NOAA Coast Watch	0.6°C	1981-2011
	Pathfinder			
SST	AMSR-E	NOAA Coast Watch	0.7°C	2002-2010
SST	GOES	NOAA Coast Watch	1°C	2001-2010*
SST	MODIS-	NASA JPL	0.5°C	2000-2011
	Terra			
Hydrographic	Various	UK Meteorological	0.5°C for T	1950-2011
data		Office	0.1 for S	

from a randomly chosen year 1999 analysis after assimilation. [Andersson, Järvinen (99)]



- 4 standard deviations seem to reflect a fair departure from the straight lines :  $\alpha = 16$
- Use of the same threshold for all in situ data only.

Monitoring

### Cost function





Wavelet analysis

- **Region Center-East**
- **SST anomaly**: Sea Surface Temperature minus climatological mean
- Thermocline depth anomaly Depth of the thermocline minus climatological ' mean: Thermocline assumed to be the isotherm of 11°C. Based on vertical profiles of temperatures for the year 1995.
- Along-shore anomaly: Along-shore transport along 37°N section minus climatological mean.



**Cross-shore transport:** Cross-shore transport along 500m isobathymetry section.



\*The GOES SST are seriously biased during the period 2001-2002, so they are not used in ROMS 4D-VAR until 2003.

### 4D-Var Set-up

Cost function • Control vector  $\mathbf{z} = (\mathbf{x}^T(t_0), \mathbf{f}^T, \mathbf{b}^T)^T$ , no errors model Minimize non linear function: Observation Observation operator Prior information  $J_{\rm NL} = (\mathbf{z} - \mathbf{z}^{\mathbf{b}})^T \mathbf{D}^{-1} (\mathbf{z} - \mathbf{z}^{\mathbf{b}}) + (\mathbf{y}^{\mathbf{0}} - H(\mathbf{x}))^T \mathbf{R}^{-1} (\mathbf{y}^0 - H(\mathbf{x}))$ Error covariance matrices Time assimilation windows: • **31 years**, from January 1980 to December 2010 **Overlapped cycles of 8 days**: one cycle every 4 days



• Prior state  $\mathbf{x}^{o}$  : state at the middle of the previous cycle, except the first cycle: long spinup integration of the ROMS CCS





This work was supported by the National Science Foundation (OCE-1061434) and the U.S. Office of Naval Research (N00014-10-1-0476). Any opinions, findings and conclusions or recommendation.